



### STM32100B-MCKIT motor control starter kit

## Introduction

The STM32100B-MCKIT starter kit is an integrated system designed to provide a complete, ready-to-use motor control application developed around the STMicroelectronics STM32F100 microcontroller. This starter kit is particularly suited to drive three-phase brushless permanent magnet synchronous motors and demonstrates how effectively the low-cost STM32F100 microcontrollers can be used in cost-optimized real-world motor control applications. For evaluation of higher performance systems, STM3210B-MCKIT (based on STM32F103 microcontroller) may be used.

The STM32100B-MCKIT supports Field Oriented Control (FOC) drive of three-phase permanent magnet synchronous motors (PMSM). Single-shunt resistor current measurement is supported out-of-the-box allowing closed loop torque control. Position measurement can be implemented using quadrature encoder sensors, Hall effect sensors or sensorless algorithms.

You can run the STM32100B-MCKIT starter kit in two ways:

- As a plug-and play, out-of-the-box, demo with the provided PMSM motor, in sensorless torque or speed control mode.
- In conjunction with a third-party IDE and C compiler, as a development kit for creating your own motor control application based on STM32F100.

The CD ROM in the STM32100B-MCKIT contains all relevant manuals and related documentation including:

- STM32F100 microcontroller datasheets.
- STM32 evaluation boards features, peripherals, and connectors are described in the STM32100B-EVAL user manual (UM0841).
- STM32 PMSM FOC MC library (also referenced as STM32 PMSM FOC SDK), its customization and the default program flashed onto the STM32F100B-EVAL, are described in the Quick start guide for STM32F103xx/STM32F100xx PMSM single/dual FOC SDK V3.0 (UM1080).
- STM32 PMSM FOC MC library usage is described in the STM32 FOC PMSM firmware library user and developer manuals (UM1052 and UM1053, respectively).

#### In this manual, you will find information on:

- The STM32100B-MCKIT starter kit components.
- How to set up the hardware to run the provided PMSM motor.

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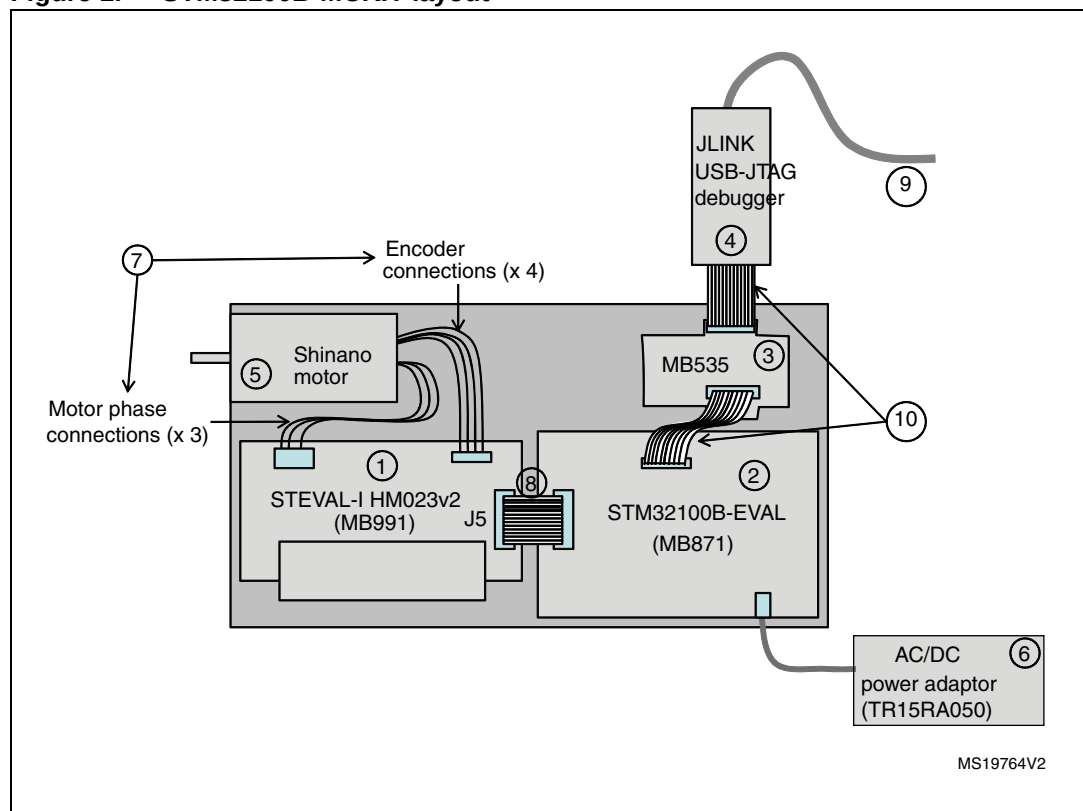
# 1 STM32100B-MCKIT hardware setup

This section provides a detailed description of the components that are included in the STM32100B-MCKIT starter kit. It also describes the default settings for a permanent magnet synchronous motor (PMSM).

## 1.1 Package checklist

[Figure 1](#) shows the layout and connections of the major components of the STM32100B-MCKIT starter kit.

**Figure 1. STM32100B-MCKIT layout**



### 1.1.1 Hardware

The STM32100B-MCKIT starter kit includes the following items:

- STEVAL-IHM023v2 (MB991) power stage evaluation board (1)  
This board is described in the STEVAL-IHM023v2 user manual (UM0723) provided on the STM32100B-MCKIT CD-ROM.
- MB871 STM32100B-EVAL evaluation board (2)  
This board is described in the STM32100B-EVAL user manual (UM0841) provided on the STM32100B-MCKIT CD-ROM.

- MB535B opto-isolation JTAG board (3)  
This board is described in the JTAG opto-isolation board user manual (UM0378) provided on the STM32100B-MCKIT CD-ROM.  
The purpose of the JTAG opto-isolation board is to provide galvanic isolation between the J-link debugger/programmer and the STM32 evaluation board. It helps to prevent accidental damage to the PC in the event of a catastrophic failure on the motor control board. This isolation barrier also solves the problem of the PC, JTAG debugger and motor control board being at different ground potentials.
- J-link USB–JTAG debugger (4)  
The SEGGER J-link USB-JTAG debugger enables you to reprogram the Flash memory of the STM32 microcontroller and to debug the software before using the application in standalone mode.
- 24V DC Shinano PMSM motor (5)  
The motor included in the STM32100B-MCKIT starter kit is a Shinano inner rotor type four-pole brushless DC motor with Hall sensor and encoder. For electrical specifications and mechanical dimensions, refer to the Shinano datasheets on the STM32100B-MCKIT CD-ROM.
- AC/DC power adaptor (TR15RA050) (6)  
To supply the MB871 board
- The following cables:
  - Motor cables (7)
  - A motor connector HE10 34-pin cable (8)
  - A USB cable (9)
  - Two JTAG cables (10)
- STM32100B-MCKIT CD-ROM

### 1.1.2 Software

The STM32100B-MCKIT CD-ROM includes the following software: STM32 PMSM FOC SDK v3.0, ST MC Workbench, a PC software for configuring the above-mentioned STM32 FOC PMSM MC library (v3.0 and later).

When you receive the STM32100B-MCKIT, the STM32 microcontroller is programmed by default with the PMSM sensorless FOC firmware. It is recommended to search for the latest available version of the firmware (contact your nearest ST office or technical support team, or look on [www.st.com](http://www.st.com)) before starting any new development.

### 1.1.3 Documentation

The STM32100B-MCKIT CD-ROM includes the following product documentation in PDF format:

- STM32F100xx high-, medium- and low-density datasheets
- STM32F10xxx reference manual
- STM32100B-MCKIT motor control kit user manual (UM1452, i.e. this manual)
- STM32 FOC PMSM MC library user manual (UM1052)
- STM32 FOC PMSM MC library developer manual (UM1053)
- Quick start guide for PMSM FOC SDK v3.0 (UM1080)
- STM32100B-EVAL user manual (UM0841)
- STEVAL-IHM023v2 power stage evaluation board user manual (UM0723)
- JTAG opto-isolation board user manual (UM0378)

### 1.1.4 Components not provided

The STM32100B-MCKIT starter kit does not include the 24 V - 3 A (minimum) power supply required to run the provided PMSM motor.

### 1.1.5 Permanent magnet synchronous motor (PMSM)

The PM synchronous motor is a rotating electric machine where the stator is a classic three-phase stator like that of an induction motor and the rotor has surface-mounted permanent magnets. In this respect, the PM synchronous motor is equivalent to an induction motor where the air gap magnetic field is produced by a permanent magnet. The use of a permanent magnet to generate a substantial air gap magnetic flux makes it possible to design highly efficient PM motors.

A PM synchronous motor is driven by sine wave voltage coupled with the given rotor position. The generated stator flux together with the rotor flux, which is generated by a rotor magnet, defines the torque, and thus speed, of the motor. The sine wave voltage output has to be applied to the three-phase winding system in such a way that the angle between the stator flux and the rotor flux is kept close to 90° to get the maximum generated torque. To meet this criterion, the motor requires electronic control for proper operation.

For a common three-phase PM synchronous motor, a standard three-phase power stage is used. The power stage uses six power transistors with independent switching. The power transistors are switched in the complementary mode. The sine wave output is generated using the space vector PWM technique.

## 1.2 Hardware configuration for PMSM motor

This section describes the procedure for operating the STM32100B-MCKIT with a PMSM motor.

When you are running the PMSM motor, follow these steps:

1. Verify that all the jumpers on the motor control board (MB991) are in their default position.  
Refer to [Table 1](#) for information on jumper settings, and if necessary, to the STEVAL-IHM023v2 user manual (UM0723) for the location of the jumpers on the board.
2. Verify that all of the STM32100B-EVAL evaluation board (MB871) jumpers are in their default position.  
Refer to [Table 2](#) for information on jumper settings, and if necessary, to the STM32100B-EVAL evaluation board user manual (UM0841) for the location of jumpers on the board.
3. Verify that the PMSM motor cables are correctly plugged into the STEVAL-IHM023v2 connectors J2 and J4.  
The STEVAL-IHM023v2, the STM32100B-EVAL evaluation board (MB871), the opto-isolation JTAG board (MB535B), and the provided PMSM motor are already assembled together over a metal support when you receive the kit.
4. Verify that the STM32100B-EVAL evaluation board and the JTAG opto-isolation board (MB535B) are connected with the provided 20-pin JTAG cable.  
In this way, the STM32100B-EVAL evaluation board automatically supplies the opto-isolation board.
5. Power up the STM32100B-EVAL evaluation board with the auxiliary AC/DC power adaptor (TR15RA050).
6. Power up the power stage board (STEVAL-IHM023v2) by connecting the output terminals of your DC power supply to the “MAINS” connector (J1).  
The provided voltage must be 24 V DC and your power supply must be able to provide a current of 3 A.

The STM32100B-MCKIT is now ready to run with the PMSM motor.

**Caution:** Before supplying power to the board, double check proper connections, make sure that there are no metal parts on, below or around the PCB and that there are no undesired earth/ground loops due to measuring equipment such as an oscilloscope.

**Table 1. STEVAL-IHM023v2 board jumper settings for a PMSM motor (default)**

| Jumper | Settings for the provided Shinano 24 V PMSM motor                | Settings for a high-voltage PMSM motor |
|--------|------------------------------------------------------------------|----------------------------------------|
| W1     | 3.3 V position                                                   |                                        |
| W3     | "< 35 V only"                                                    | "< 35 V only" or "HIGH VOLTAGE"        |
| W4     | Present                                                          |                                        |
| W5     | "R_BRAKE" position                                               |                                        |
| W6     | Not present                                                      |                                        |
| W7     | Not present                                                      |                                        |
| W8     | Present                                                          |                                        |
| W9     | Present, in "1 shunt" position (opposite to silkscreen)          |                                        |
| W10    | Present and soldered on default position of silkscreen printing  |                                        |
| W11    | Present in silkscreen position                                   |                                        |
| W13    | Present, in "1 shunt" position (opposite to silkscreen printing) |                                        |
| W14    | Not present                                                      |                                        |
| W16    | Present (opposite to silkscreen printing)                        |                                        |

**Table 2. STM32100B-EVAL board jumper settings for a PMSM motor (default)**

| Jumper   | Description                                                                              |
|----------|------------------------------------------------------------------------------------------|
| JP10     | Set to PSU position to supply the STM32100B-EVAL evaluation board through the jack (CN8) |
| JP6      | Not fitted (Hall effect sensors/tachogenerator signal filtering)                         |
| SW1, SW2 | Both set to "0" position to boot from embedded user Flash                                |

## 1.3 Power supply connections

Refer to Section 3.3.1 of the STEVAL-IHM023v2 user manual (UM0723) to know more about the possible connections for the STEVAL-IHM023v2 power supply stage.

## 2 Running and customizing the starter kit

When you receive the STM32100B-MCKIT starter kit, the STM32 microcontroller is already programmed with the PMSM sensorless FOC firmware, enabling you to immediately run the PMSM motor included in the kit.

It is also possible to change some starter kit components, for instance the provided PMSM 24V Shinano motor can be replaced with any PMSM/BLDC three-phase motor, and can also use a different control stage and/or power stage.

As the ST standard motor control connector is fitted on most of the available ST evaluation boards, it is possible to use different power stages (with different rated power, supply voltage, nominal current,...) in conjunction with different STM32 evaluation boards (STM32100E-EVAL, STEVAL-IHM022v1,...) on condition that the STM32 FOC PMSM SDK v3.0 is properly configured through the ST MC Workbench PC software.

For more details refer to:

- [www.st.com](http://www.st.com) to find out about the available products and/or systems evaluation boards
- Products and/or systems evaluation boards documentation for information related to the hardware configuration of these boards
- The 'Quickstart guide for STM32 PMSM MC Library v3.0' (UM1080, §3.2) to know more about firmware customization and programming

## **3 Safety warnings**

### **3.1 General**

In operation, the STM32100B-MCKIT starter kit has noninsulated wires, moving or rotating parts (when connected to a motor), as well as hot surfaces. In case of improper use, incorrect installation or misuse, there is danger of serious personal injury and damage to property. All operations, installation and maintenance are to be carried out by skilled technical personnel (applicable accident prevention rules must be observed).

When the motor control board is supplied with voltages greater than 30 V AC/DC, all of the board and components must be considered “hot”, and any contact with the board must be avoided. The operator should stay away from the board as well (risk of projection of material in case of component destruction, especially when powering the board with high voltages). The rotating parts of motors are also a source of danger.

The STM32100B-MCKIT starter kit contains electrostatic sensitive components which may be damaged through improper use.

### **3.2 Intended use**

The STM32100B-MCKIT starter kit is made of components designed for demonstration purposes and must not be included in electrical installations or machinery. Instructions about the setup and use of the STM32100B-MCKIT starter kit must be strictly observed.

### **3.3 Operation**

After disconnecting the board from the voltage supply, several parts and power terminals must not be touched immediately because of possible energized capacitors or hot surfaces.

### **3.4 Important notice to users**

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## Appendix A Additional information

### A.1 Recommended reading

This documentation describes how to use the STM32100B-MCKIT Starter Kit. Additional information can be found in the following documents:

- STM32F100xx low- and medium- density datasheets
- STM32F10xxx reference manual (RM0008)
- STMicroelectronics motor control application notes
- STM32100B-EVAL evaluation board user manual (UM0841)
- JTAG opto-isolation board user manual (UM0378)
- STEVAL-IHM023v2 power stage evaluation board user manual (UM0723)
- STM32 FOC PMSM MC library user manual (UM1052)
- STM32 FOC PMSM MC library developer manual (UM1053)
- Quick start guide for PMSM FOC SDK v3.0 (UM1080)

All the above documents can be found on the STM32100B-MCKIT CD-ROM.

### A.2 Software upgrades

The latest versions of the STM32 motor control libraries are available, free of charge, from our sales offices.

### A.3 Getting technical support

Technical assistance is provided free to all customers. For technical assistance, documentation and information about products and services, please refer to your local STMicroelectronics partner.

## 4 Revision history

**Table 3. Document revision history**

| Date         | Revision | Changes                                                                                                                            |
|--------------|----------|------------------------------------------------------------------------------------------------------------------------------------|
| 09-Sept-2011 | 1        | Initial release                                                                                                                    |
| 16-Sept-2011 | 2        | Modified description of TR15RA050 in <a href="#">Section 1.1.1</a><br>Added customization information in <a href="#">Chapter 2</a> |

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