

preliminary

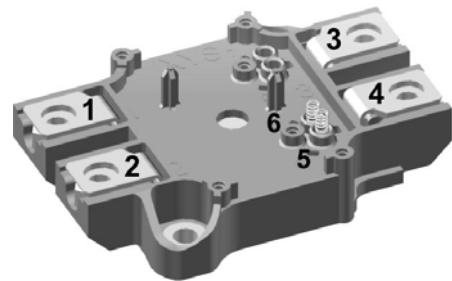
# Thyristor Module

$V_{RRM}$  = 2x 1600 V  
 $I_{TAV}$  = 200 A  
 $V_T$  = 1.13 V

## Phase leg

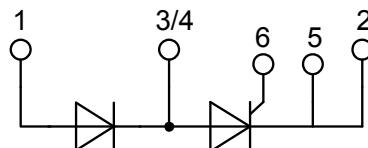
### Part number

MCMA200PD1600SA



Backside: isolated

E72873



### Features / Advantages:

- Thyristor for line frequency
- Planar passivated chip
- Long-term stability
- Copper base plate with Direct Copper Bonded Al<sub>2</sub>O<sub>3</sub>-ceramic
- Spring contacts for solder-free driver connection

### Applications:

- Line rectifying 50/60 Hz
- Softstart AC motor control
- DC Motor control
- Power converter
- AC power control
- Lighting and temperature control

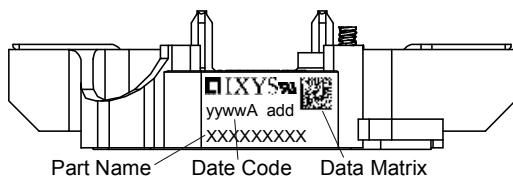
### Package: SimBus A

- Isolation Voltage: 4800 V~
- Industry standard outline
- RoHS compliant
- Gate: Spring contacts for solder-free PCB-mounting
- Height: 17 mm
- Base plate: Copper internally DCB isolated
- Advanced power cycling

## Rectifier

Symbol	Definition	Conditions	min.	typ.	max.	Unit
$V_{RSM/DSM}$	max. non-repetitive reverse/forward blocking voltage	$T_{VJ} = 25^\circ C$			1700	V
$V_{RRM/DRM}$	max. repetitive reverse/forward blocking voltage	$T_{VJ} = 25^\circ C$			1600	V
$I_{RD}$	reverse current, drain current	$V_{RD} = 1600 V$ $V_{RD} = 1600 V$	$T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		200 10	$\mu A$ mA
$V_T$	forward voltage drop	$I_T = 200 A$ $I_T = 400 A$ $I_T = 200 A$ $I_T = 400 A$	$T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		1.16 1.40 1.13 1.44	V V
$I_{TAV}$	average forward current	$T_C = 85^\circ C$	$T_{VJ} = 140^\circ C$		200	A
$I_{T(RMS)}$	RMS forward current	180° sine			314	A
$V_{T0}$ $r_T$	threshold voltage slope resistance } for power loss calculation only		$T_{VJ} = 140^\circ C$		0.81 1.57	V $m\Omega$
$R_{thJC}$	thermal resistance junction to case				0.15	K/W
$R_{thCH}$	thermal resistance case to heatsink			0.08		K/W
$P_{tot}$	total power dissipation		$T_C = 25^\circ C$		760	W
$I_{TSM}$	max. forward surge current	$t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$ $t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$ $t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$ $t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$	$T_{VJ} = 45^\circ C$ $V_R = 0 V$ $T_{VJ} = 140^\circ C$ $V_R = 0 V$		6.00 6.48 5.10 5.51	kA kA
$I^2t$	value for fusing	$t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$ $t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$ $t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$ $t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$	$T_{VJ} = 45^\circ C$ $V_R = 0 V$ $T_{VJ} = 140^\circ C$ $V_R = 0 V$		180.0 174.7 130.1 126.3	$kA^2s$ $kA^2s$ $kA^2s$ $kA^2s$
$C_J$	junction capacitance	$V_R = 400 V$ $f = 1 \text{ MHz}$	$T_{VJ} = 25^\circ C$		273	pF
$P_{GM}$	max. gate power dissipation	$t_p = 30 \mu s$ $t_p = 300 \mu s$	$T_C = 140^\circ C$		120 60 8	W W W
$P_{GAV}$	average gate power dissipation					
$(di/dt)_{cr}$	critical rate of rise of current	$T_{VJ} = 140^\circ C; f = 50 \text{ Hz}$ repetitive, $I_T = 600 A$ $t_p = 200 \mu s; di_G/dt = 0.5 A/\mu s;$ $I_G = 0.5 A; V_D = \frac{2}{3} V_{DRM}$ non-repet., $I_T = 200 A$			150	A/ $\mu s$
$(dv/dt)_{cr}$	critical rate of rise of voltage	$V_D = \frac{2}{3} V_{DRM}$ $R_{GK} = \infty$ ; method 1 (linear voltage rise)	$T_{VJ} = 140^\circ C$		1000	V/ $\mu s$
$V_{GT}$	gate trigger voltage	$V_D = 6 V$	$T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$		2.5 2.6	V V
$I_{GT}$	gate trigger current	$V_D = 6 V$	$T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$		150 200	mA mA
$V_{GD}$	gate non-trigger voltage	$V_D = \frac{2}{3} V_{DRM}$	$T_{VJ} = 140^\circ C$		0.2	V
$I_{GD}$	gate non-trigger current				10	mA
$I_L$	latching current	$t_p = 30 \mu s$ $I_G = 0.5 A; di_G/dt = 0.5 A/\mu s$	$T_{VJ} = 25^\circ C$		300	mA
$I_H$	holding current	$V_D = 6 V$ $R_{GK} = \infty$	$T_{VJ} = 25^\circ C$		200	mA
$t_{gd}$	gate controlled delay time	$V_D = \frac{1}{2} V_{DRM}$ $I_G = 0.5 A; di_G/dt = 0.5 A/\mu s$	$T_{VJ} = 25^\circ C$		2	$\mu s$
$t_q$	turn-off time	$V_R = 100 V; I_T = 200 A; V_D = \frac{2}{3} V_{DRM}$ $T_{VJ} = 140^\circ C$ $di/dt = 10 A/\mu s; dv/dt = 20 V/\mu s; t_p = 200 \mu s$		150		$\mu s$

Package SimBus A			Ratings			
Symbol	Definition	Conditions	min.	typ.	max.	Unit
$I_{RMS}$	RMS current	per terminal			300	A
$T_{stg}$	storage temperature		-40		125	°C
$T_{VJ}$	virtual junction temperature		-40		140	°C
<b>Weight</b>				152		g
$M_D$	mounting torque		3		5	Nm
$M_T$	terminal torque		2.5		5	Nm
$d_{Spp/App}$	creepage distance on surface   striking distance through air	terminal to terminal	14.0	10.0		mm
$d_{Spb/Apb}$		terminal to backside	14.0	10.0		mm
$V_{ISOL}$	isolation voltage	t = 1 second t = 1 minute 50/60 Hz, RMS; $I_{ISOL} \leq 1$ mA	4800 4000			V V



#### Part number

M = Module  
 C = Thyristor (SCR)  
 M = Thyristor  
 A = (up to 1800V)  
 200 = Current Rating [A]  
 PD = Phase leg  
 1600 = Reverse Voltage [V]  
 SA = SimBus A

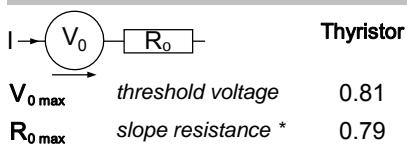
Ordering	Part Number	Marking on Product	Delivery Mode	Quantity	Code No.
Standard	MCMA200PD1600SA	MCMA200PD1600SA	Blister	9	510380

Similar Part	Package	Voltage class
MCMA200P1600SA	Simbus A	1600

#### Equivalent Circuits for Simulation

\* on die level

$T_{VJ} = 140$  °C

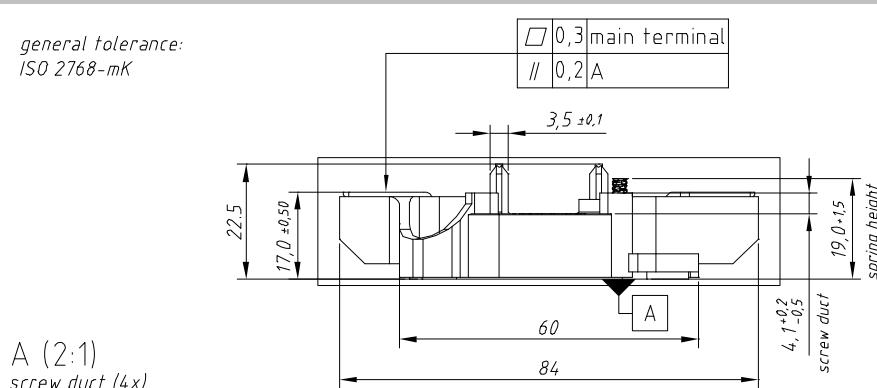


V

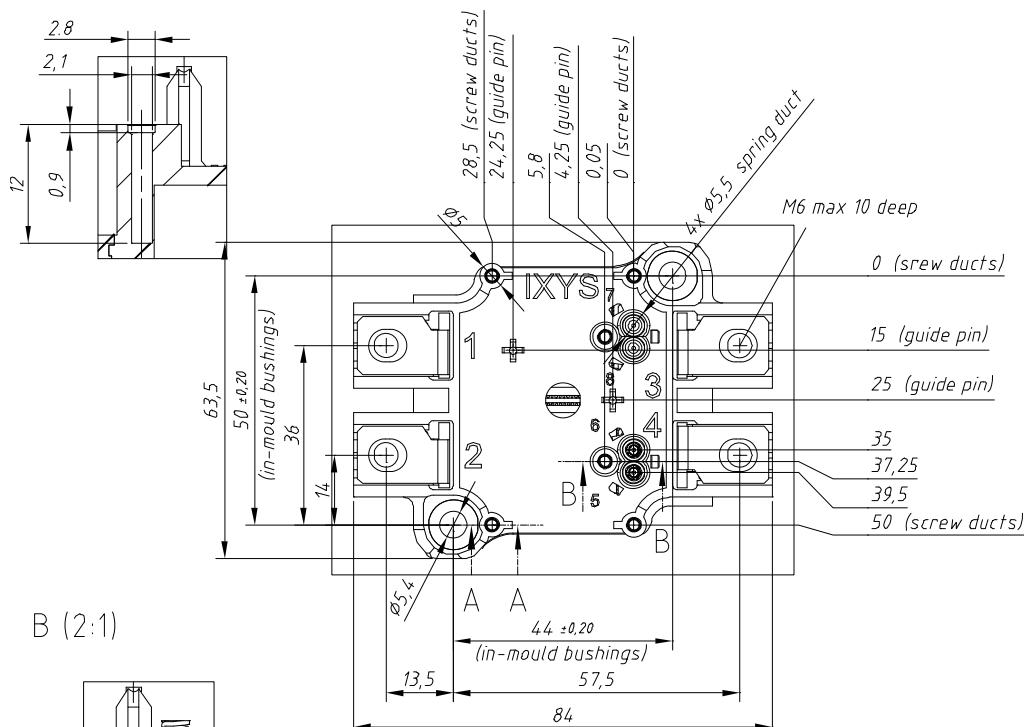
mΩ

## Outlines SimBus A

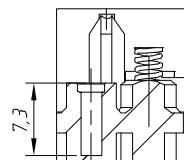
general tolerance:  
ISO 2768-mK



A (2:1)  
screw duct (4x)



B (2:1)



Rules for the contact PCB:  
 - spring landing pad =  $\phi 3.5 \pm 0.2$ ; position tolerance  $\pm 0.1$   
 - holes guide pins =  $\phi 4 \pm 0.1$ ; position tolerance  $\pm 0.1$   
 - holes PCB screws =  $2.9 \pm 0.1$ ; position tolerance  $\pm 0.1$

