
Si1120 EVALUATION KIT USER'S GUIDE

1. Kit Contents

The Si1120 Evaluation Kit contains the following items:

- Si1120 Evaluation Board
- C8051F930 Target Board
- Si1120EK Quick Start Guide
- AC to DC Power Adapter
- USB Debug Adapter (USB to Debug Interface)
- 2 USB Cables

2. Introduction

The Si1120EK is intended as an evaluation and development platform for the Si1120 infrared proximity and ambient light sensor. Two PCBs are included in the kit: the Si1120 EVB shown in Figure 1, and the C8051F930-TB shown in Figure 2. Although the C8051F930-TB is part of the development kit, the documentation in this user's guide will focus on the Si1120 EVB and the example firmware. For more specific information on the C8051F930 TB, refer to the "C8051F930-DK User's Guide". The main components of the Si1120 EVB are the Si1120 sensor (U1), the infrared emitters (D1 through D7), and header J1 which allows for selection between different infrared emitters on the board. On this PCB, the infrared emitters used are OSRAM part number SFH 4650-Z. These emitters have a power rating of 45 mW and a half-angle of 20 degrees. Other emitters with different characteristics may also be used, depending on the specific application requirements.

The example firmware for the kit measures the infrared light energy detected by the Si1120 while each of three infrared emitters are independently activated. The infrared light from these emitters will be reflected back to the Si1120 by any object that is placed in proximity to the sensor. X, Y, and Z positions can be calculated from these measurements. If no object is close enough to the board, the measured signal levels will fall below pre-determined thresholds, and the position calculations will not update. The example firmware is intended to be used in conjunction with the Si1120 Performance Analysis Tool to provide user feedback. In addition to calculating the current position, the firmware is able to detect different gestures from the infrared sensor, as described in Table 1 on page 5. The Si1120's ambient light sensor (ALS) is also monitored by the firmware, which can determine the type of ambient light present.

Note: The touchless infrared position detection implemented in the example is patent pending.

3. Getting Started

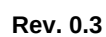
The Si1120 Evaluation Kit requires some PC software to be installed, as well as some basic hardware setup of the boards included in the kit.

3.1. Software Download and Installation

1. Browse to the Si1120 Evaluation Kit page at the URL <http://www.silabs.com/Si1120EK>.
2. Download and install the latest CP210x USB-to-UART Virtual COM Port (VCP) driver. This driver is necessary to establish serial communications with the board.
3. Download and install the latest version of the Optical Sensors Programmer's Toolkit. The Si1120 Performance Analysis Tool is part of this package, and is an integral part of the example firmware functionality.
4. (Optional) Download and install the Silicon Laboratories IDE and the Si1120 Evaluation Kit package. This will enable programming and debugging of the example source code. Note that the firmware is pre-loaded into the board during manufacturing. The IDE and board package are needed to upgrade or modify the firmware.

- Refer to Figure 3 for the full hardware connection diagram.





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Figure 4. Header J1 Setup

4. Software Overview

There are several software packages available to support the example firmware that is pre-loaded on the board. The primary package that is required for functionality is the Si1120 Performance Analysis Tool, which can be used to collect data from the board over the USB interface and display it graphically on screen.

Optional software packages include the Silicon Labs Integrated Development Environment (IDE), and the Si1120 Evaluation Kit package. The Silicon Labs IDE provides a means of developing code for the C8051F930 and uses the USB Debug Adapter to program the MCU and perform in-system debugging. For users wishing to modify the example code or download the latest version of firmware into the board, the Si1120 Evaluation Kit installation package contains board-specific materials such as the latest version of the pre-built firmware .HEX image and the firmware example source code.

4.1. Using the Si1120EK With the Si1120 Performance Analysis Tool

The Si1120 Evaluation Kit is supported by the Si1120 Performance Analysis Tool. The Performance Analysis Tool allows users to see real-time measured infrared proximity and ambient light measurements from the Si1120 in a graphical form, as well as the calculated values for distance from each of the infrared LEDs and the X, Y, and Z positions. Additionally, recognized gestures and the ambient light conditions can be displayed in dedicated group windows. The communications interface to the Si1120 EVB is provided over USB (P3) via the CP2103 USB-to-UART bridge.

To use the Performance Analysis Tool with the Si1120 Evaluation Kit:

1. Connect the C8051F930-TB to the PC using a USB cable.
2. Launch the Performance Analysis Tool from the “Start” menu.
3. Select the board from the “Devices” menu (it will normally show up as the last COM port in the list).
4. Select the channels you wish to display on the picture of the Si1120 EVB that appears. The individual channels available are described in “4.1.1. Channel Selection” .
5. Click the green “Acquisition” arrow to begin collecting data.

Figure 5 shows an example of the Performance Analysis Tool output when connected to the board. To generate the graph, a hand was moved above the Si1120EVB. The selected traces shown are the calculated X and Y positions. The green trace represents the X position, while the yellow trace represents the Y position of the hand above the board.

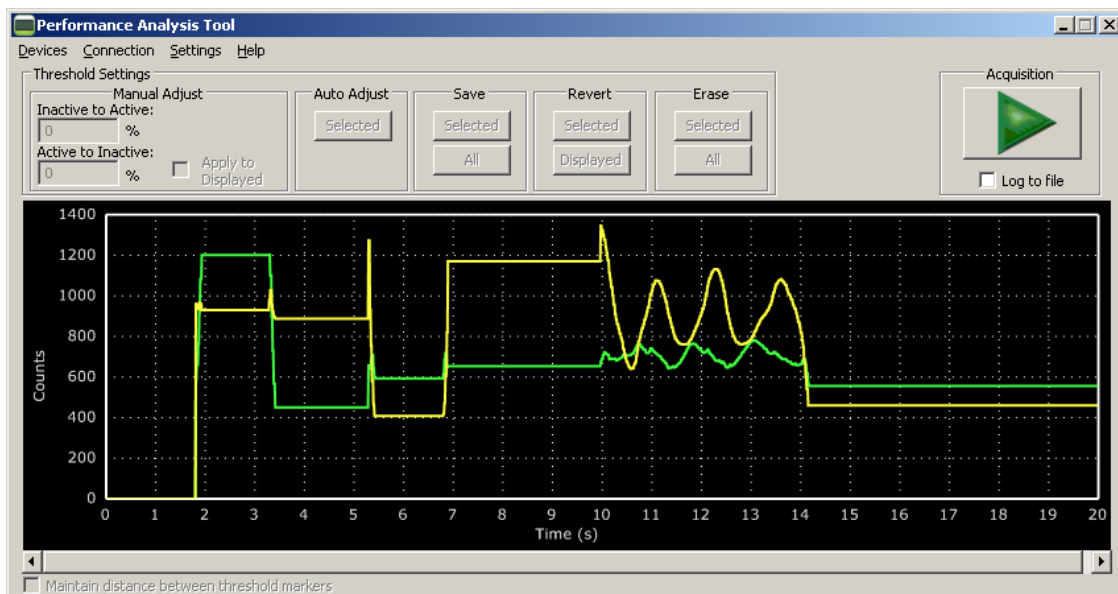


Figure 5. Performance Analysis Tool Main Window

4.1.1. Channel Selection

Selecting which channels to display is a simple matter of checking the appropriate boxes over the board photograph, shown in Figure 7.

4.1.2. Gestures and Ambient Light Conditions

In addition to infrared and ambient light measurements and distance calculations, the example firmware contains algorithms for gesture recognition and ambient light condition detection. When connected to the board with the Performance Analysis Tool, two group windows will appear, as shown in Figure 6. When a gesture is recognized by firmware, the gesture name and parameter information will be added to the top of the 3D Gesture group. Four gestures are supported by the example code. The parameters for each gesture are listed in Table 1. The detected ambient light conditions (Sunlight, Incandescent/Halogen, or Fluorescent/CFL) will be displayed in the Light Type.

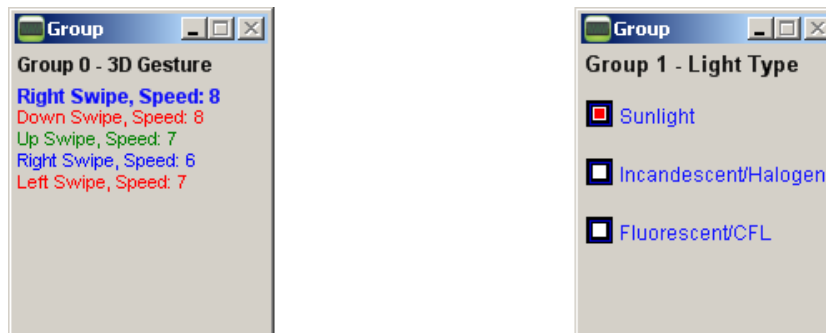


Figure 6. Performance Analysis Tool Group Windows

Table 1. Recognized Gestures

Gesture Name	Parameter	Parameter Range	Description of Action
Swipe Left	Speed	1 18 (Slow to Fast)	Move hand rapidly from the right side to the left side of the board.
Swipe Right	Speed	1 18 (Slow to Fast)	Move hand rapidly from the left side to the right side of the board.
Swipe Up	Speed	1 18 (Slow to Fast)	Move hand rapidly from the bottom to the top of the board.
Swipe Down	Speed	1 18 (Slow to Fast)	Move hand rapidly from the top to the bottom of the board.

4.2. Silicon Laboratories IDE

The Silicon Laboratories IDE integrates a source-code editor, a source-level debugger, and an in-system Flash programmer. This tool can be used to develop and debug code for the C8051F930 MCU. The use of several third-party compilers and assemblers is supported by the IDE.

4.2.1. IDE System Requirements

The Silicon Laboratories IDE requirements:

- Pentium-class host PC running Microsoft Windows 2000 or newer.
- One available USB port.

4.2.2. Third Party Toolsets

The Silicon Laboratories IDE has native support for many 8051 compilers. The full list of natively supported tools is as follows:

- Keil
- IAR

- Raisonance
- Tasking
- SDCC

4.2.3. Downloading the Example Firmware Image

Example firmware source code as well as a pre-built .HEX image are available from the Si1120-EK web page at <http://www.silabs.com/products/sensors/infraredsensors/Pages/si1120ek.aspx>. The prebuilt .HEX image can be downloaded directly into the C8051F930 target board. The firmware source code and an example IDE project are configured to use a default path of `C:\SiLabs\Optical_Sensors\Si1120\Firmware`. Follow the steps below to update or refresh the .HEX image in the C8051F930-TB:

1. Connect the hardware as described in "3.2. Hardware Setup" on page 2.
2. Launch the Silicon Labs IDE, and click on *Options->Connection Options*.
3. Select "USB Debug Adapter" and then select the connected adapter from the list (it should show up as "EC3" followed by a serial number).
4. Select "C2" as the debug interface, and press "OK".
5. Connect to the board by pressing the "Connect" icon, or using the keyboard shortcut Alt+C.
6. Click on the "Download" icon, or use the keyboard shortcut Alt+D.
7. In the download dialog window, click "Browse".
8. Change to Files of Type "Intel Hex (*.hex)" and then browse to select the file.
9. Click "Open" then "Download".
10. To run the new image, either press "Run" or "Disconnect" in the IDE.

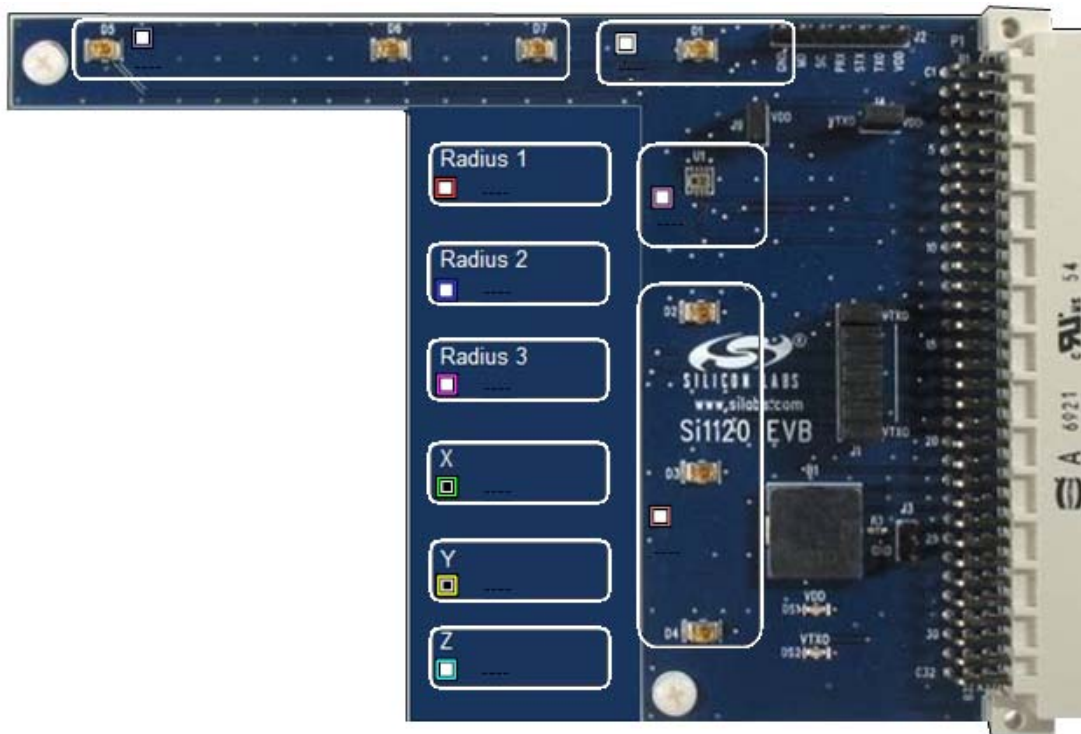


Figure 7. Channel Selection

There are three different types of measurements available from the example firmware:

1. Raw infrared proximity and ambient light measurements. The infrared channels are indicated by the check boxes near the infrared emitters (D1-D7), while the ambient light channel is the check box over the Si1120 (U1).

The data for these channels represents a measurement of the duration of the Si1120's PRX low time, as seen by the C8051F930 MCU. The Y axis indicates the number of 6.125 MHz clock cycles that occurred while PRX was low. The maximum output limit of the Si1120 is 2 ms, which would correspond to 12250 counts of a 6.125 MHz clock.

2. Linearized distance measurements for each IR channel. The raw proximity values output from the Si1120 will be exponentially larger the closer an object is to the sensor. The channels labeled "Radius 1", "Radius 2" and "Radius 3" are linearizations of the raw data output from the sensor when illuminating the three different selected emitters. To use the example effectively, the shorting blocks on header J1 should be set according to the diagram in Figure 1. This will select D1, D4, and D7 as the three reference emitters.
3. Calculated coordinate measurements. The linearized IR proximity measurements are used to calculate X (left-to-right), y (up-to-down) and a Z (far-to-near) measurements.

Due to the nature of infrared proximity measurements, the object's size and reflectivity will have an impact on the values measured.

Rev. 0.3



Figure 8. Si1120 EVB Schematic

DOCUMENT CHANGE LIST

Revision 0.2 to Revision 0.3

- Replaced QuickSense Studio references and instructions with Optical Sensors Programmer's Toolkit.
- Updated instructions for downloading and using Si1120-EK example code.

CONTACT INFORMATION

Silicon Laboratories Inc.
400 West Cesar Chavez
Austin, TX 78701
Tel: 1+(512) 416-8500
Fax: 1+(512) 416-9669
Toll Free: 1+(877) 444-3032

Please visit the Silicon Labs Technical Support web page:
<https://www.silabs.com/support/pages/contacttechnicalsupport.aspx>
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