Incremental 25-mm-dia. Rotary Encoder

E6A2-C

CSM_E6A2-C_DS_E_3_1

Compact Encoder (External Diameter: 25 mm)

- Models with origin output (phase Z) for positioning applications.
- Resolution of 500 ppr in an Encoder with an external diameter of only 25 mm.



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Be sure to read *Safety Precautions* on page 3.

Ordering Information

Encoders [Refer to Dimensions on page 4.]

Output phases	Power supply voltage	Output configuration	Resolution (pulses/rotation)	Model		
Phase A	5 to 12 VDC	Voltage output	10, 20, 60, 100, 200, 300, 360	E6A2-CS3E (resolution) 0.5M		
			500	Example: E6A2-CS3E 10P/R 0.5M		
		Open-collector output	10, 20, 60, 100, 200, 300, 360	E6A2-CS3C (resolution) 0.5M		
			500	Example: E6A2-CS3C 10P/R 0.5M		
	12 to 24 VDC		10, 20, 60, 100, 200, 300, 360	E6A2-CS5C (resolution) 0.5M		
			500	Example: E6A2-CS5C 10P/R 0.5M		
Phases A and B	5 to 12 VDC	Voltage output	100, 200, 360	E6A2-CW3E (resolution) 0.5M		
			500	Example: E6A2-CW3E 100P/R 0.5M		
		Open-collector output	100, 200, 360	E6A2-CW3C (resolution) 0.5M		
			500	Example: E6A2-CW3C 100P/R 0.5M		
	12 to 24 VDC		100, 200, 360	E6A2-CW5C (resolution) 0.5M		
			500	Example: E6A2-CW5C 100P/R 0.5M		
Phases A, B, and Z	5 to 12 VDC	Voltage output	100, 200, 360	E6A2-CWZ3E (resolution) 0.5M		
			500	Example: E6A2-CWZ3E 100P/R 0.5M		
		Open-collector output	100, 200, 360	E6A2-CWZ3C (resolution) 0.5M		
			500	Example: E6A2-CWZ3C 100P/R 0.5M		
	12 to 24 VDC		100, 200, 360	E6A2-CWZ5C (resolution) 0.5M		
			500	Example: E6A2-CWZ5C 100P/R 0.5M		

Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks			
Coupling	E69-C04B	Provided with the product.			
Servo Mounting Bracket	E69-1	Provided with the E6A2-CWZ			

Refer to Accessories for details.

E6A2-C

Ratings and Specifications

Item	Model	E6A2-CS3E	E6A2-CS3C	E6A2-CS5C	E6A2-CW3E	E6A2-CW3C	E6A2-CW5C	E6A2- CWZ3E	E6A2- CWZ3C	E6A2- CWZ5C
Power su voltage	pply	5 VDC –5% to 12 V +10%, ripple (p-p): 5% max. (p-p): 5% max.		12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.	5 VDC –5% to 12 V +10%, ripple (p-p): 5% max. (p-p): 5% max.		12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.	5 VDC -5% to 12 V +10% ripple (p-p): 5% max. (p-p): 5% max. (p-p): 5% max.		12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.
Current consump	tion*1	30 mA max. 20 mA max.		30 mA max.	20 mA max.		50 mA max.	30 mA max.		
Resolutio rotation)	n (pulses/	10, 20, 60, 100, 200, 300, 360, 500			100, 200, 360,	500				
Output ph	nases	Phase A			Phases A and B			Phases A, B, and Z		
Output co	onfiguration	Voltage out- put Open-collector output		Voltage out- put	Open-collector output		Voltage out- put	Open-collector output		
Output ca	ut capacity Ut ca		Applied voltage: 30 VDC max. Sink current: 30 mA max. Residual voltage: 0.4 V max. (at sink current of 30 mA)		Output resis- tance: $2 k\Omega$ Output cur- rent: 20 mA max. Residual volt- age: 0.4 V max. (Output cur- rent: 20 mA max.)	Applied voltage: 30 VDC max. Sink current: 30 mA max. Residual voltage: 0.4 V max. (at sink current of 30 mA)		Output resistance: $2 \ k\Omega$ Output current: 20 mA max. Residual voltage: 0.4 V max. (Output current: 20 mA max.)	Applied voltage: 30 VDC max. Sink current: 30 mA max. Residual voltage: 0.4 V max. (at sink current of 30 mA)	
Maximum frequency	response /*2	30 kHz								
Phase difference	se difference			Phase difference between phases A and B: 90°±45°						
Output du	ity factor	50±25%								
Rise and fall times of output		1.0 μs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μ s max. (Cable length: 500 mm, Control output volt- age: 5 V, Load resistance: 1 k Ω)		1.0 μs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μ s max. (Cable length: 500 mm, Control output volt- age: 5 V, Load resistance: 1 k Ω)		1.0 μs max. (Cable length: 500 mm, Sink current: 10 mA)	1.0 μ s max. (Cable length: 500 mm, Control output volt- age: 5 V, Load resistance: 1 k Ω)	
Starting to	orque	1 mN·m max.			I	I			I	
Moment o	of inertia	$1 \times 10^{-7} \text{ kg} \cdot \text{m}^2$	max.							
Shaft	Radial	10 N								
loading	Thrust	50 N	50 N							
Maximum permissib	le speed	5,000 r/min								
Ambient t range	emperature	Operating: -10 to 55°C (with no icing), Storage: -25 to 80°C (with no icing)								
Ambient I range	numidity	Operating/storage: 35% to 85% (with no condensation)								
Insulation	resistance	20 M Ω min. (at 500 VDC) between current-carrying parts and case								
Dielectric	strength	500 VAC, 50/60 Hz for 1 min between current-carrying parts and case								
Vibration	resistance	Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions								
Shock res	sistance	Destruction: 500m/s ² 3 times each in X, Y, and Z directions								
Degree of protection	1*3	IEC 60529 IP50								
Connectio	on method	Pre-wired Models (Standard cable length: 500 mm)								
Material		Case: Aluminum alloy, Main unit: Aluminum, Shaft: SUS420J2, Mounting Bracket: Galvanized iron								
Weight (packed s	tate)	Approx. 35 g								
Accessor	ies	Coupling, Servo Mounting Bracket (provided with the E6A2-CWZ□), Hexagonal wrench, Instruction manual								

*1. An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON.
 *2. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

Maximum electrical response speed (rpm) = <u>Maximum response frequency</u> × 60 Resolution

This means that the E6A2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed. *3. No protection is provided against water or oil.

E6A2-C

I/O Circuit Diagrams



2. Output A leads B by 1/4 T±1/8 T when the shaft revolves clockwise, while A lags behind B by 1/4 T±1/8 T when the shaft revolves counterclockwise.

Safety Precautions

Refer to Warranty and Limitations of Liability.

<u> (</u>WARNING

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.

Precautions for Correct Use

Do not use the Encoder under ambient conditions that exceed the ratings.

• Wiring

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

E6A2-C

(Unit: mm)

Dimensions

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

Encoder





Accessories (Order Separately)

Servo Mounting Bracket Coupling E69-C04B E69-1 Refer to Accessories for details.

Read and Understand This Catalog

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

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- · Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this catalog.
- Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations.
- · Systems, machines, and equipment that could present a risk to life or property.

Please know and observe all prohibitions of use applicable to the products.

NEVER USE THE PRODUCTS FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO ADDRESS THE RISKS, AND THAT THE OMRON PRODUCTS ARE PROPERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.

PROGRAMMABLE PRODUCTS

OMRON shall not be responsible for the user's programming of a programmable product, or any consequence thereof.

Disclaimers

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